# **Mathematical modelling**

Lecture 8, April 5th, 2022

Faculty of Computer and Information Science University of Ljubljana

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### Areas bounded by plane curve

I. Let 
$$f(t) = \begin{bmatrix} x(t) \\ y(t) \end{bmatrix}$$
,  $t \in [a, b]$   
 $x'(t) > 0$ 

The area of the quadrilateral bounded by the curve and the x-axis is

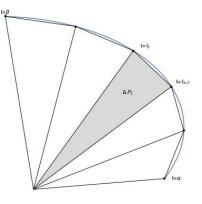
$$P = \int_{x(a)}^{x(b)} |y(x)| \, dx = \int_{a}^{b} |y(t)| x'(t) \, dt$$

Problem: the area under one arc of the cycloid:

$$x(t) = at - a\sin t$$
,  $y(t) = a - a\cos t$ ,

$$P = \int_0^{2\pi} a^2 (1 - \cos t)^2 dt = a^2 \int_0^{2\pi} \left(\frac{3}{2} - 2\cos t + \frac{1}{2}\cos(2t)\right) dt = 3a^2 \pi.$$

II. The area of the triangular region bounded by the curve  $f(t), t \in [a, b]$ , and the two end-point position vectors f(a) and f(b):



$$P = \frac{1}{2} \int_{a}^{b} |x(t)y'(t) - y(t)x'(t)| dt.$$

## Proof of the area formula

An approximate value of the area is the sum of areas of triangles obtained by subdividing the interval [a, b] into n intervals of length  $\Delta t = (b - a)/n$ .

The area of a triangle with vertices (0,0),  $f(t_i)$ ,  $f(t_{i+1})$  is

$$egin{aligned} &\Delta P_i = rac{1}{2} \| f(t_{i+1}) imes f(t_i) \| \doteq rac{1}{2} \| (f(t_i) + f'(t_i) \Delta t) imes f(t_i) \| \ &= rac{1}{2} \| f'(t_i) imes f(t_i) \| \Delta t = rac{1}{2} | y'(t_i) imes (t_i) - imes'(t_i) y(t_i) | \Delta t, \end{aligned}$$

where the last equlatiy follows from the calculation

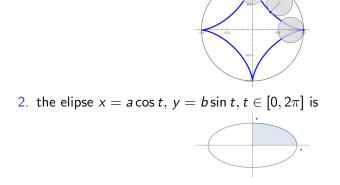
$$f'(t_i) \times f(t_i) = (x'(t_i), y'(t_i), 0) \times (x(t_i), y(t_i), 0)$$
  
= (x'(t\_i)y(t\_i) - y'(t\_i)x(t\_i), 0, 0).

The area is obtained by adding these and letting  $n \to \infty$ :

$$P = \lim_{n \to \infty} \frac{1}{2} \sum_{i=0}^{n-1} |y'(t_i)x(t_i) - x'(t_i)y(t_i)| \Delta t$$
$$= \frac{1}{2} \int_a^b |x(t)y'(t) - y(t)x'(t)| dt.$$

Problem: the area bounded by

1. the asteroid  $x(t) = \cos^3 t$ ,  $y(t) = \sin^3 t$ ,  $t \in [0, 2\pi]$  is



Hint. In both problems use the identities

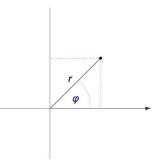
$$\sin^2 t = \frac{1}{2}(1 - \cos(2t)), \qquad \cos^2 t = \frac{1}{2}(1 + \cos(2t)).$$

In the first problem all you have to really integrate after subtractions of some terms is  $1 - \cos^2(2t)$ . The results are  $\frac{3\pi}{8}$  for the first and  $ab\pi$  for the second problem.

# Curves in the polar plane

Polar coordinates of a point in the plane are

- distance to the origin  $r, r \ge 0$ , and
- ▶ polar angle  $\varphi$ , determined up to a multiple of  $2\pi$ , defined for  $r \neq 0$ .



Usually the polar axis corresponds to the positive part of the x-axis, so

• 
$$x = r \cos \varphi$$
,  $y = r \sin \varphi$   
•  $r = \sqrt{x^2 + y^2}$ ,  $\tan \varphi = \frac{y}{x}$ 

A curve in polar coordinates is given by  $r = r(\varphi)$ ,  $\varphi \in I \subset \mathbb{R}$ .

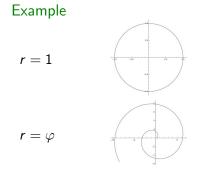
Rule. If  $r(\varphi) < 0$ , then the point on the curve at an angle  $\varphi$  is equal to

$$(x(\varphi), y(\varphi)) := |r(\varphi)|(\cos \varphi, \sin \varphi) \cdot e^{i\pi}.$$

In other words, we reflect the point

 $|r(\varphi)|(\cos \varphi, \sin \varphi)$ 

over the origin.

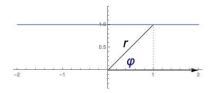


unit circle

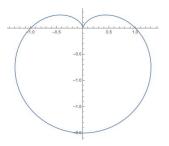
Arhimedean spiral

Example

$$\underline{\text{line } y = 1}, \quad r = \frac{1}{\sin \varphi}$$

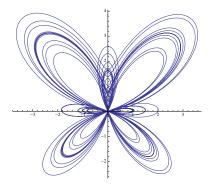


cardioid,  $r = 1 - \sin \varphi$ 



## Example a butterfly

 $r = \sin^5\left(rac{arphi - \pi}{12}
ight) + e^{\sinarphi} - 2\cos(4arphi)$ 



Matlab files:

https://zalara.github.io/Algoritmi/curves\_polar.m

A parametrization of the curve with parameter being the polar angle is:

$$f(\varphi) = \left[\begin{array}{c} r(\varphi)\cos(\varphi) \\ r(\varphi)\sin(\varphi) \end{array}\right], \varphi \in I.$$

### Example

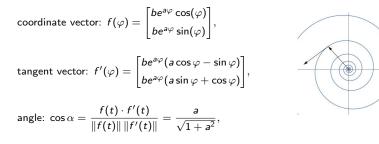
The hyperbolic spiral 
$$r = \frac{1}{\varphi}$$
 is parametrized by  $f(t) = \begin{bmatrix} \frac{\cos \varphi}{\varphi} \\ \frac{\sin \varphi}{\varphi} \end{bmatrix}$ ,

as 
$$\varphi \to 0$$
,  $r(\varphi) \to \infty$   
 $x(\varphi) = \frac{\cos \varphi}{\varphi} \to \infty$   
 $y(\varphi) = \frac{\sin \varphi}{\varphi} \to 1$   
as  $\varphi \to \infty$ ,  $r(\varphi) \to 0$ 

The tangent vector to the curve at a point  $r(\varphi)$  is given by

$$f'(\varphi) = \begin{bmatrix} r'(\varphi)\cos(\varphi) - r(\varphi)\sin(\varphi) \\ r'(\varphi)\sin(\varphi) + r(\varphi)\cos(\varphi) \end{bmatrix}$$

Problem: compute the angle between the coordinate vector of a point on the **logarithmic spiral**  $r(\varphi) = be^{a\varphi}$  and the tangent vector at that point.



so the angle is independent of  $\varphi$  so it is the same at every point on the curve.

# Area in polar coordinates

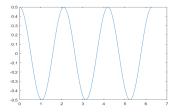
$$P = \frac{1}{2} \int_{\alpha}^{\beta} |xy' - x'y| \, d\varphi = \frac{1}{2} \int_{\alpha}^{\beta} r^2 \, d\varphi$$

Indeed:

$$xy' - x'y = r\cos\varphi(r'\sin\varphi + r\cos\varphi) - r\sin\varphi(r'\cos\varphi - r\sin\varphi)$$
$$= r^2(\cos^2\varphi + \sin^2\varphi) = r$$

Problem: what is the area of one petal of the clover  $r(\varphi) = \frac{\cos(3\varphi)}{2}$ ?

To plot the clover it is convenient to sketch the function  $r(\varphi)$  first.



#### Useful angles are

$$\frac{\varphi \quad 0 \quad \frac{\pi}{6} \quad \frac{2\pi}{6} \quad \frac{3\pi}{6} \quad \frac{4\pi}{6} \quad \frac{5\pi}{6} \quad \frac{6\pi}{6} \quad \frac{7\pi}{6} \quad \frac{8\pi}{6} \quad \frac{9\pi}{6} \quad \frac{10\pi}{6} \quad \frac{11\pi}{6} \quad \frac{12\pi}{6} \quad \frac{12$$

# Motion in $\mathbb{R}^3$

Let  $\mathbf{r}(t) = f(t)$  be the position vector of a particle in space at time t,  $1 \le t \le 2$ .

Then  $\mathbf{v}(t) = \mathbf{r}'(t)$  is its velocity and  $\mathbf{a}(t) = \mathbf{r}''(t)$  is its acceleration at time t.

Problem: Let  $\mathbf{r}(t) = \begin{bmatrix} t^2 \\ 2t \\ \log t \end{bmatrix}$ .

- 1. Compute its position, velocity and acceleration at time t = 1, and the length of its path between t = 1 and t = 2.
- 2. If at time t = 2 the particle leaves its path and goes off in the tangential direction with constant velocity, where will it be at time t = 3? What is the length of its path from t = 1 to t = 3?

1. Since 
$$\mathbf{r}'(t) = \begin{bmatrix} 2t \\ 2 \\ 1/t \end{bmatrix}$$
 and  $\mathbf{r}''(t) = \begin{bmatrix} 2 \\ 0 \\ -1/t^2 \end{bmatrix}$ , the position, velocity and acceleration  
at  $t = 1$  are  
 $\mathbf{r}(1) = \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix}$ ,  $\mathbf{v}(1) = \begin{bmatrix} 2 \\ 2 \\ 1 \end{bmatrix}$   $\mathbf{a}(1) = \begin{bmatrix} 2 \\ 0 \\ -1 \end{bmatrix}$ 

and the length of path

$$\int_{1}^{2} \|\mathbf{r}'(t)\| dt = \int_{1}^{2} \sqrt{4t^{2} + 4 + (1/t)^{2}} dt = \int_{1}^{2} (2t + 1/t) dt = [2t^{2}/2 + \log t]_{1}^{2} = 3 + \log 2$$

2. The tangent line at t = 2, and the position at t = 3 are:

$$L_2(t) = \begin{bmatrix} 4 \\ 4 \\ \log 2 \end{bmatrix} + (t-2) \begin{bmatrix} 4 \\ 2 \\ 1/2 \end{bmatrix}, L_2(3) = \begin{bmatrix} 8 \\ 6 \\ \log 2 + 1/2 \end{bmatrix}$$

and length of the path along the tangent from t = 2 to t = 3 is

$$\int_{2}^{3} \|\mathbf{v}(2)\| \, dt = 9/2,$$

so the total length is  $\log 2 + 7 + \frac{1}{2}$ .

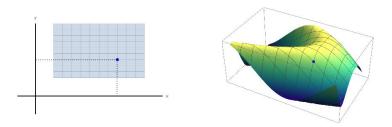
### 3.4. Parametric surfaces

A parametric surface in  $\mathbb{R}^m$  is given by a continuous vector function

$$f: D o \mathbb{R}^m, \qquad D \subset \mathbb{R}^2.$$

We will consider the case m = 3:

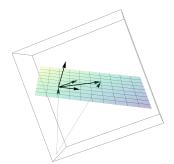
$$\begin{bmatrix} u \\ v \end{bmatrix} \in D \qquad \qquad f(u,v) = \begin{bmatrix} x(u,v) \\ y(u,v) \\ z(u,v) \end{bmatrix} \in \mathbb{R}^3$$



### Example

1. A parametric plane through a given point  $\mathbf{r}_0 \in \mathbb{R}^3$  with given (noncolinear) vectors  $\mathbf{e}_1$  and  $\mathbf{e}_2$ :

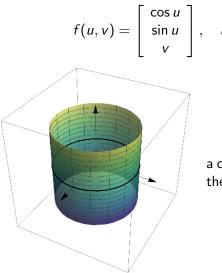
$$f(u,v) = \mathbf{r}_0 + u\mathbf{e}_1 + v\mathbf{e}_2, \quad u,v \in \mathbb{R},$$



The normal to the plane is  $\mathbf{n} = \mathbf{e}_1 \times \mathbf{e}_2 \neq 0$ .

The equation the plane:  $(\mathbf{r} - \mathbf{r}_0) \cdot \mathbf{n} = 0$ Matlab file: https://zalara.github.io/Algoritmi/plane.m

17/25



2.

$$u \in [0, 2\pi], v \in [0, 1]$$

a cylinder with radius 1 and axis the *z*-axis

### Matlab file: https://zalara.github.io/Algoritmi/cylinder.m

For every point  $f(u_0, v_0)$  on the surface there are two <u>coordinate curves</u> through it:

- ►  $f(u_0, v)$ ,
- ►  $f(u, v_0)$ ,

both lie on the surface.

### Example

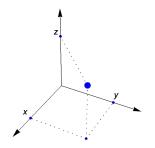
- 1. In the parametrized plane  $f(u, v) = r_0 + ue_1 + ve_2$ ,  $e_1 \times e_2 \neq 0$ , coordinate curves are lines parallel to  $e_2$  for a fixed  $u = u_0$  and to  $e_1$  for a fixed  $v = v_0$ .
- 2. In the cylinder, coordinate curves  $u = u_0$  are vertical lines, and  $v = v_0$  are circles.

### Coordinate systems in $\mathbb{R}^3$

The parameters u and v in surface parametrizations often have a geometric meaning.

For example, they could be two coordinates from one of the standard coordinate systems in  $\mathbb{R}^3$ :

Cartesian coordinates x, y, z (we know these well)



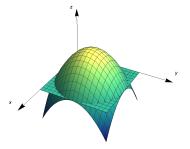
Example

$$f(x,y) = \begin{bmatrix} x \\ y \\ 1 - (x-1)^2 - (y-1)^2 \end{bmatrix}$$
,  $0 \le x, y \le 2$ 

The surface is the graph  $z = 1 - (x - 1)^2 - (y - 1)^2$ ,

Coordinate curves: intersection with planes

 $x = x_0$  and  $y = y_0$ 



Matlab file:

https://zalara.github.io/Algoritmi/surfaces\_coordinate\_curves.m

#### Cylindrical coordinates:

 $\rho \geq 0$  distance from z axis, polar radius in plane z = 0

 $\varphi$  polar angle in plane z = 0

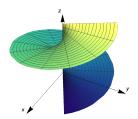


Conversion to cartesian coordinates:  $x = \rho \cos \varphi, y = \rho \sin \varphi, z = z$ 

Example  $f(u, v) = \begin{bmatrix} u \cos v \\ u \sin v \\ v \end{bmatrix}$ 

Coordinate curves:

 $u = u_0$ : helix with radius  $u_0$  $v = v_0$ : ray from *z*-axis with polar angle and height  $v_0$ 



#### Matlab file: https://zalara.github.io/Algoritmi/cylindrical\_coordinates\_helix.m

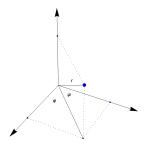
Spherical coordinates:  $r, \varphi, \psi$ , where

 $r, r \ge 0$ : distance to the origin,

 $\varphi$ : polar angle in plane z = 0

 $\psi$ ,  $-\pi/2 \le \psi \le \pi/2$ : azimuthal angle between the coordinate vector and plane z = 0,

$$\begin{split} \psi &= \pi/2; \text{ positive part of } z \text{ axis} \\ \psi &= 0; \text{ plane } z = 0 \\ \psi &= -\pi/2 \text{ negative part of } z\text{-axis} \end{split}$$



Conversion to cartesian coordinates:  $x = r \cos \varphi \cos \psi$ ,  $y = r \sin \varphi \cos \psi$ ,  $z = r \sin \psi$ 

Conversion to cylindrical coordinates:  $\rho = r \cos \psi$ ,  $z = r \sin \psi$ 

Example

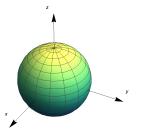
$$f(u, v) = \begin{bmatrix} \cos u \cos v \\ \sin u \cos v \\ \sin v \end{bmatrix}, \ 0 \le u \le 2\pi, -\pi/2 \le v \le \pi/2$$

The surface is the unit sphere r = 1

Coordinate curves:

 $u = u_0$ : latitude  $u = u_0$ 

 $v = v_0$ : longitude  $v = v_0$ 



Matlab file:

https://zalara.github.io/Algoritmi/spherical\_coordinates.m